

## DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR

- HIGH SPEED:
  - $t_{PD}$  = 25 ns (TYP.) at  $V_{CC}$  = 6V
- LOW POWER DISSIPATION:

STAND BY STATE:

 $I_{CC}=4\mu A$  (MAX.) at  $T_A=25^{\circ}C$ 

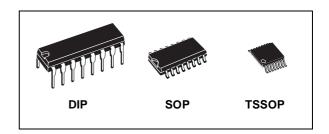
ACTIVE STATE :

- $I_{CC}$ =200μA (TYP.) at  $V_{CC}$  = 6V HIGH NOISE IMMUNITY:
- $V_{NIH} = V_{NIL} = 28 \% V_{CC} (MIN.)$
- SYMMETRICAL OUTPUT IMPEDANCE: |I<sub>OH</sub>| = I<sub>OL</sub> = 4mA (MIN)
- BALANCED PROPAGATION DELAYS:  $t_{PLH} \cong t_{PHL}$
- WIDE OPERATING VOLTAGE RANGE: V<sub>CC</sub> (OPR) = 2V to 6V
- WIDE OUTPUT PULSE WIDTH RANGE :  $t_{WOUT} = 120 \text{ ns} \sim 60 \text{ s}$  OVER AT  $V_{CC} = 4.5 \text{ V}$
- PIN AND FUNCTION COMPATIBLE WITH 74 SERIES 4538



The M74HC4538 is an high speed CMOS MONOSTABLE MULTIVIBRATOR fabricated with silicon gate  $\,\mathrm{C}^2\mathrm{MOS}$  technology.

Each multivibrator features both a negative A, and a positive B, edge triggered input, either of which can be used as an inhibit input. Also included is a clear input that when taken low resets the one shot. The monostable multivibrator are



#### **ORDER CODES**

PACKAGE	TUBE	T & R
DIP	M74HC4538B1R	
SOP	M74HC4538M1R	M74HC4538RM13TR
TSSOP		M74HC4538TTR

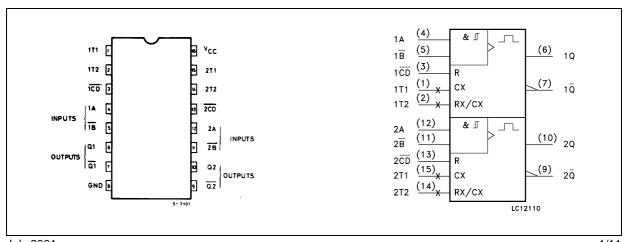
retriggerable. That is, they may be triggered repeatedly while their outputs are generating a pulse and the pulse will be extended. Pulse width stability over a wide range of temperature and supply is achieved using linear CMOS techniques.

The output pulse equation is simply:

PW = 0.7 (R)(C) where PW is in seconds, R in Omhs and C is in Farads.

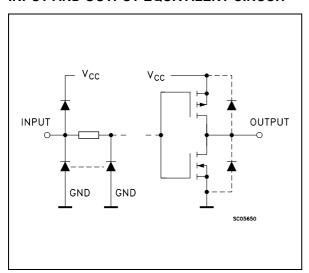
All inputs are equipped with protection circuits against static discharge and transient excess voltage.

#### PIN CONNECTION AND IEC LOGIC SYMBOLS



July 2001 1/11

## INPUT AND OUTPUT EQUIVALENT CIRCUIT



## **PIN DESCRIPTION**

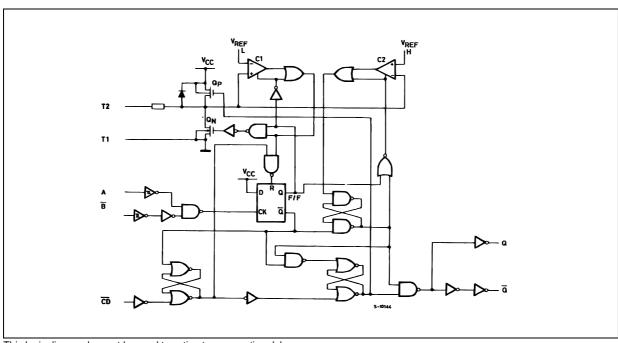
PIN No	SYMBOL	NAME AND FUNCTION
1, 15	1T1, 2T1	External Capacitor Connections
2, 14	1T2, 2T2	External Resistor/ Capacitor Connections
3, 13	1CD, 2CD	Direct Reset Inputs (Active Low)
4, 12	1A, 2A	Trigger Inputs (LOW to HIGH, Edge-Triggered)
5, 11	1 <del>B</del> , 2 <del>B</del>	Trigger Inputs (HIGH to LOW, Edge Triggered)
6, 10	Q1, Q2	Pulse Outputs
7, 9	Q1, Q2	Complementary Pulse Outputs
8	GND	Ground (0V)
16	Vcc	Positive Supply Voltage

## **TRUTH TABLE**

	INPUTS		ОИТІ	PUTS	NOTE
Α	B	CD	Q	Q	NOTE
	Н	Н	J		OUTPUT ENABLE
Х	L	Н	L	Н	INHIBIT
Н	Х	Н	L	Н	INHIBIT
L	7_	Н			OUTPUT ENABLE
Х	Х	L	L	Н	INHIBIT

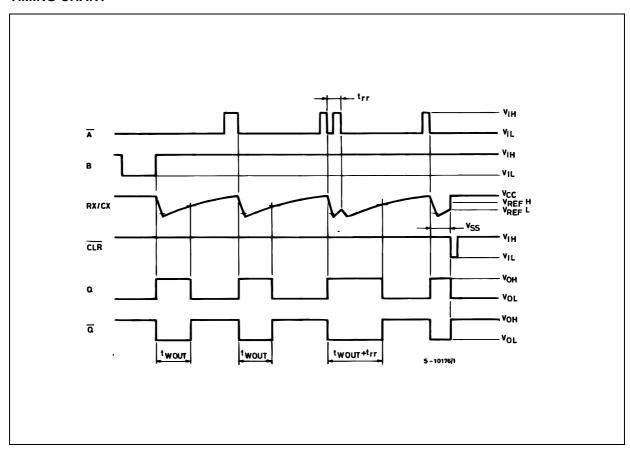
X : Don't Care

## **SYSTEM DIAGRAM**

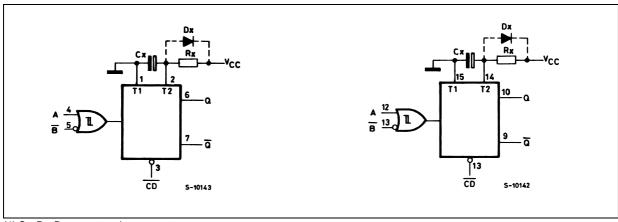


This logic diagram has not be used to estimate propagation delays

#### **TIMING CHART**



## **BLOCK DIAGRAM**



(1) Cx, Rx, Dx are external components.
(2) Dx is a clamping diode.

The external capacitor is charged to Vcc in the stand-by-state, i.e. no trigger. When the supply voltage is turned off Cx is discharged mainly trough an internal parasitic diode(see figures). If Cx is sufficiently large and Vcc decreases rapidly, there will be some possibility of damaging the I.C. with a surge current or latch-up. If the voltage supply filter capacitor is large enough and Vcc decrease slowly, the surge current is automatically limited and damage to the I.C. is avoided. The maximum forward current of the parasitic diode is approximately 20 mA. In cases where Cx is large the time taken for the supply voltage to fall to 0.4 Vcc can be calculated as follows:

 $t_f \ge (\text{Vcc - 0.7}) \times \text{Cx/20mA}$ In cases where  $t_f$  is too short an external clamping diode is required to protect the I.C. from the surge current.

#### **FUNCTIONAL DESCRIPTION**

STAND-BY STATE

The external capacitor,Cx, is fully charged to Vcc in the stand-by state. Hence, before triggering, transistor Qp and Qn (connected to the Rx/Cx node) are both turned-off. The two comparators that control the timing and the two reference voltage sources stop operating. The total supply current is therefore only leakage current.

TRIGGER OPERATION

Triggering occurs when:

1 st) A is "LOW" and  $\overline{B}$  has a falling edge;

2 nd) B is "HIGH" and A has a rising edge;

After the multivibrator has been retriggered comparator C1 and C2 start operating and Qn is turned on. Cx then discharges through Qn. The voltage at the node Rx/Cx external falls.

When it reaches  $V_{REFL}$  the output of comparator C1 becomes low. This in turn reset the flip-flop and Qn is turned off.

At this point C1 stops functioning but C2 continues to operate.

The voltage at R/C external begins to rise with a time constant set by the external components Rx, Cx.

Triggering the multivibrator causes Q to go high after internal delay due to the flip-flop and the gate. Q remains high until the voltage at R/C external rises again to  $V_{REFH}$ . At this point C2 output goes low and G goes low. C2 stop

operating. That means that after triggering when the voltage R/C external returns to  $V_{REFH}$  the multivibrator has returned to its MONOSTABLE STATE. In the case where Rx  $\cdot$  Cx are large enough and the discharge time of the capacitor and the delay time in the I.C. can be ignored, the width of the output pulse tw (out) is as follows:

 $t_{W(OUT)} = 0.72 \text{ Cx} \cdot \text{Rx}$ 

### **RE-TRIGGERED OPERATION**

When a second triggere pulse follows the first its effect will depend on the state of the multivibrator. If the capacitor Cx is being charged the voltage level of Rx/Cx external falls to  $V_{REFL}$  again and Q remains High i.e. the retrigger pulse arrives in a time shorter than the period Rx  $\cdot$  Cx seconds, the capacitor charging time constant. If the second trigger pulse is very close to the initial trigger pulse it is ineffective; i.e. the second trigger must arrive in the capacitor discharge cycle to be ineffective; Hence the minimum time for a second trigger to be effective, trr (MIN.) depends on Vcc and Cx

#### **RESET OPERATION**

CD is normally high. If CD is low, the trigger is not effective because Q output goes low and trigger control flip-flop is reset.

Also transistor Op is turned on  $\underline{\text{and}}$  Cx is charged quickly to Vcc. This means if  $\overline{\text{CD}}$  input goes low the IC becomes waiting state both in operating and non operating state.

#### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	Supply Voltage	-0.5 to +7	V
V <sub>I</sub>	DC Input Voltage	-0.5 to V <sub>CC</sub> + 0.5	V
Vo	DC Output Voltage	-0.5 to V <sub>CC</sub> + 0.5	V
I <sub>IK</sub>	DC Input Diode Current	± 20	mA
I <sub>OK</sub>	DC Output Diode Current	± 20	mA
Io	DC Output Current	± 25	mA
I <sub>CC</sub> or I <sub>GND</sub>	DC V <sub>CC</sub> or Ground Current	± 50	mA
$P_{D}$	Power Dissipation	500(*)	mW
T <sub>stg</sub>	Storage Temperature	-65 to +150	°C
$T_L$	Lead Temperature (10 sec)	300	°C

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied

(\*) 500mW at 65 °C; derate to 300mW by 10mW/°C from 65°C to 85°C

### **RECOMMENDED OPERATING CONDITIONS**

Symbol	Parameter	Value	Unit		
V <sub>CC</sub>	Supply Voltage	2 to 6	V		
VI	Input Voltage	0 to V <sub>CC</sub>	V		
V <sub>O</sub>	Output Voltage	0 to V <sub>CC</sub>	V		
T <sub>op</sub>	Operating Temperature	-55 to 125	°C		
	Input Rise and Fall Time (CD only)	$V_{CC} = 2.0V$	0 to 1000	ns	
t <sub>r</sub> , t <sub>f</sub>		$V_{CC} = 4.5V$	0 to 500	ns	
		0 to 400	ns		
Сх	External Capacitor		NO LIMITATION	pF	
Rx	External Resistor	5K to 1M	Ω		
100		Vcc ≥ 3V	1K to 1M	22	

The Maximum allowable values of Cx and Rx are a function of leakage of capacitor Cx, the leakage of device and leakage due to the board layout and surface resistance. Susceptibility to externally induced noise may occur for  $Rx > 1M\Omega$ 

## **DC SPECIFICATIONS**

		Test Condition		Value							
Symbol	mbol Parameter		V <sub>CC</sub>		T <sub>A</sub> = 25°C			85°C	-55 to 125°C		Unit
		(V)		Min.	Тур.	Max.	Min.	Max.	Min.	Max.	
V <sub>IH</sub>	High Level Input	2.0		1.5			1.5		1.5		
	Voltage	4.5		3.15			3.15		3.15		V
		6.0		4.2			4.2		4.2		
$V_{IL}$	Low Level Input	2.0				0.5		0.5		0.5	
	Voltage	4.5				1.35		1.35		1.35	V
		6.0				1.8		1.8		1.8	
V <sub>OH</sub>	High Level Output	2.0	I <sub>O</sub> =-20 μA	1.9	2.0		1.9		1.9		
	Voltage	4.5	I <sub>O</sub> =-20 μA	4.4	4.5		4.4		4.4		
		6.0	I <sub>O</sub> =-20 μA	5.9	6.0		5.9		5.9		٧
		4.5	I <sub>O</sub> =-4.0 mA	4.18	4.31		4.13		4.10		
		6.0	I <sub>O</sub> =-5.2 mA	5.68	5.8		5.63		5.60		
V <sub>OL</sub>	Low Level Output	2.0	I <sub>O</sub> =20 μA		0.0	0.1		0.1		0.1	
	Voltage	4.5	I <sub>O</sub> =20 μA		0.0	0.1		0.1		0.1	
		6.0	I <sub>O</sub> =20 μA		0.0	0.1		0.1		0.1	V
		4.5	I <sub>O</sub> =4.0 mA		0.17	0.26		0.33		0.40	
		6.0	I <sub>O</sub> =5.2 mA		0.18	0.26		0.33		0.40	
II	Input Leakage Current	6.0	$V_I = V_{CC}$ or GND			± 0.1		± 1		± 1	μΑ
II	Input Leakage Current	6.0	$V_I = V_{CC}$ or GND Rext/Cext			± 0.1		± 1		± 1	μΑ
I <sub>CC</sub>	Quiescent Supply Current	6.0	$V_I = V_{CC}$ or GND			4		40		80	μΑ
I <sub>CC</sub>	Quiescent Supply	2.0	$V_I = V_{CC}$ or GND		40	120		160		200	μΑ
	Current	4.5	Pin 2 or 14		0.2	0.3		0.4		0.6	mA
		6.0	$V_{IN} = V_{CC}/2$		0.3	0.6		0.8		1.0	mA



# AC ELECTRICAL CHARACTERISTICS ( $C_L = 50 \text{ pF}$ , Input $t_r = t_f = 6 \text{ns}$ )

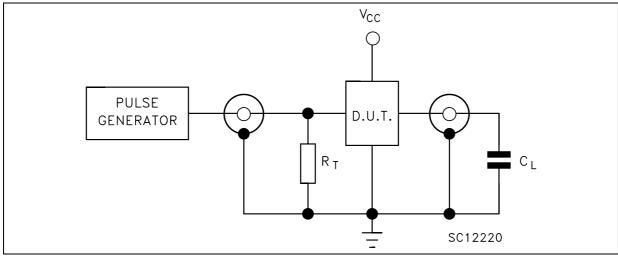
		7	Test Co	ndition				Value			Value						
Symbol	Parameter	v <sub>cc</sub>			Т	A = 25°	C	-40 to	85°C	-55 to	125°C	Unit					
		(V)			Min.	Тур.	Max.	Min.	Max.	Min.	Max.						
t <sub>TLH</sub> t <sub>THL</sub>	Output Transition	2.0				30	75		95		110						
	Time	4.5				8	15		19		22	ns					
		6.0				7	13		16		19						
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay	2.0				120	250		315		375						
	Tim <u>e</u> (A, B - Q, Q)	4.5				30	50		63		75	ns					
	, ,	6.0				25	43		54		64						
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay	2.0				100	195		245		295						
	Time (CD - Q, Q)	4.5				25	39		49		59	ns					
		6.0				20	33		42		50						
t <sub>WOUT</sub>	Output Pulse Width	2.0		$Rx = 5K\Omega$		540	1200		1500		1800						
		4.5	Cx=0	$Rx = 1K\Omega$		180	250		320		375	ns					
		6.0		Rx= 1KΩ		150	200		260		320						
		2.0	0	0.04 F	70	83	96	70	96	70	96						
		4.5	$Cx = 0.01\mu F$ $Rx = 10K\Omega$		69	77	85	69	85	69	85	μs					
		6.0	N	= 10K22	69	77	85	69	85	69	85						
		2.0	Cx = 0.1μF Rx = 10KΩ		0.67	0.75	0.83	0.67	0.83	0.67	0.9	ms					
		4.5			0.67	0.73	0.77	0.67	0.77	0.67	0.8						
		6.0	111	- 101(22	0.67	0.73	0.77	0.67	0.77	0.67	0.8						
$\Delta t_{WOUT}$	Output Pulse Width Error Between Circuits in Same Package					±1						%					
t <sub>W(H)</sub>	Minimum Pulse	2.0				30	75		95		110						
t <sub>W(L)</sub>	Width	4.5	1			8	15		19		22	ns					
, ,	$(A,\overline{B})$	6.0	1			7	13		16		19						
t <sub>W(L)</sub>	Minimum Pulse	2.0				30	75		95		110						
	Width	4.5				8	15		19		22	ns					
	(CD)	6.0				7	13		16		19						
t <sub>REM</sub>	Minimum Clear	2.0				0	15		15		20						
	Removal Time	4.5				0	5		5		7	ns					
		6.0				0	5		5								
t <sub>rr</sub>	Minimum Retrigger	2.0		_ 0.1 ::E		380											
	Time	4.5		$= 0.1 \mu F$ x = 1KΩ		92						ns					
		6.0		11122		72											
		2.0		_ 0.015		6											
		4.5		= 0.01μF x = 1KΩ		1.4						μs					
		6.0		KX = 1V77		1.2											

### **CAPACITIVE CHARACTERISTICS**

		1	est Condition	Value							
Symbol	Parameter	v <sub>cc</sub>		T <sub>A</sub> = 25°C			-40 to 85°C		-55 to 125°C		Unit
	(V)	Min.	Тур.	Max.	Min.	Max.	Min.	Max.			
C <sub>IN</sub>	Input Capacitance	5.0			5	10		10		10	pF
C <sub>PD</sub>	Power Dissipation Capacitance (note 1)	5.0			70						pF

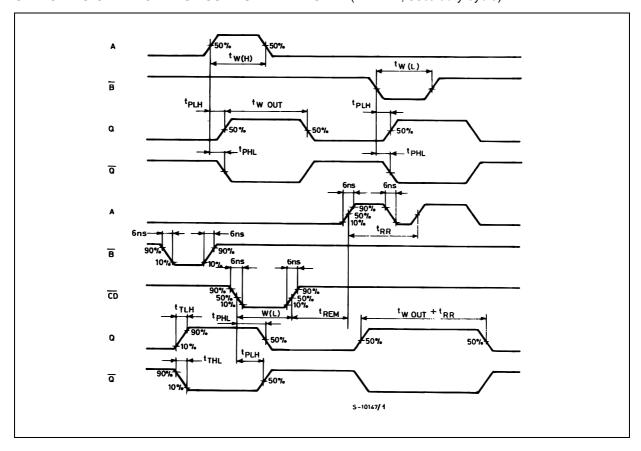
<sup>1)</sup>  $C_{PD}$  is defined as the value of the IC's internal equivalent capacitance which is calculated from the operating current consumption without load. (Refer to Test Circuit). Average operating current can be obtained by the following equation.  $I_{CC(opr)} = C_{PD} \times V_{CC} \times f_{IN} + I_{CC}$  Duty/100 + Ic/2(per monostable) ( $I_{cc}$ ': Active Supply current) (Duty: %)

### **TEST CIRCUIT**



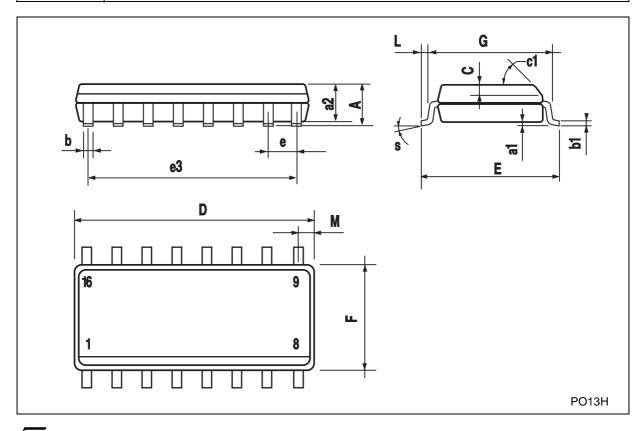
 $C_L$  = 50pF or equivalent (includes jig and probe capacitance)  $R_T$  =  $Z_{OUT}$  of pulse generator (typically 50 $\Omega$ )

## SWITCHING CHARACTERISTICS TEST WAVEFORM (f=1MHz; 50% duty cycle)



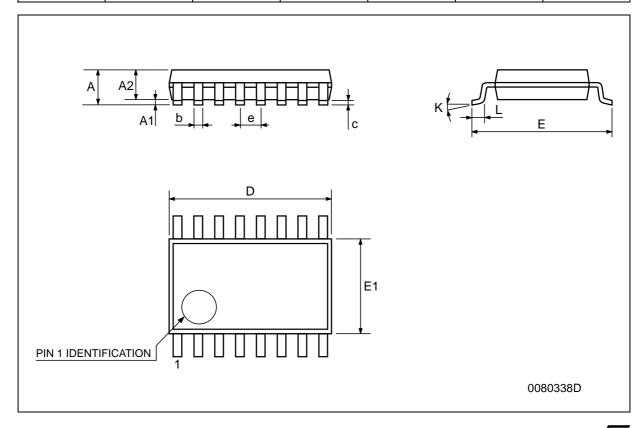
## **SO-16 MECHANICAL DATA**

DIM		mm.		inch					
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.			
Α			1.75			0.068			
a1	0.1		0.2	0.003		0.007			
a2			1.65			0.064			
b	0.35		0.46	0.013		0.018			
b1	0.19		0.25	0.007		0.010			
С		0.5			0.019				
c1			45°	(typ.)	•				
D	9.8		10	0.385		0.393			
Е	5.8		6.2	0.228		0.244			
е		1.27			0.050				
e3		8.89			0.350				
F	3.8		4.0	0.149		0.157			
G	4.6		5.3	0.181		0.208			
L	0.5		1.27	0.019		0.050			
М			0.62			0.024			
S			8° (	max.)	•	•			



## **TSSOP16 MECHANICAL DATA**

DIM.		mm.		inch				
DIWI.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.		
А			1.2			0.047		
A1	0.05		0.15	0.002	0.004	0.006		
A2	0.8	1	1.05	0.031	0.039	0.041		
b	0.19		0.30	0.007		0.012		
С	0.09		0.20	0.004		0.0089		
D	4.9	5	5.1	0.193	0.197	0.201		
E	6.2	6.4	6.6	0.244	0.252	0.260		
E1	4.3	4.4	4.48	0.169	0.173	0.176		
е		0.65 BSC			0.0256 BSC			
К	0°		8°	0°		8°		
L	0.45	0.60	0.75	0.018	0.024	0.030		



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